

## **Course Specifications**

Course Title:	Classical Mechanics 3	
Course Code:	PHY2503	
Program:	Physics	
Department:	Physics	
College:	Applied Sciences	
Institution:	Umm Al-Qura University	











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#### A. Course Identification

1. Credit hours: 4
2. Course type
a. University College Department 🗹 Others
b. Required J Elective
3. Level/year at which this course is offered: Level 6 <sup>th</sup> /2 <sup>nd</sup> year
4. Pre-requisites for this course (if any): Classical Mechanics 2
5. Co-requisites for this course (if any):

6. Mode of Instruction (mark all that apply)

No	Mode of Instruction	Contact Hours	Percentage
1	Traditional classroom	40	100%
2	Blended		115011.55.11
3	E-learning		
4	Distance learning		
5	Other		

7. Contact Hours (based on academic semester)

No	Activity	Contact Hours
1	Lecture	40
2	Laboratory/Studio	i
3	Tutorial	
4	Others (specify)	
	Total	40

## B. Course Objectives and Learning Outcomes

### 1. Course Description

This course covers the study of the mechanics of rigid bodies in plane motion, in three dimensions, and their applications. Moreover, the course covers the Lagrangian mechanics as well as a discussion of Hamilton's equations and their applications in solving some mechanical problems.

#### 2. Course Main Objective

The student will be able to

- Calculate the center of mass of a rigid body.
- Calculate the moment of inertia of a rigid body that rotated about a fixed axis.
- Describe the theorems of static equilibrium of rigid body.
- Describe Euler's equation of motion of a rigid body.
- Solve mechanical problems using Lagrangian and Hamiltonian formalisms.

3. Course Learning Outcomes

CLOs				
1	Knowledge and Understanding			
1.1	Define the physical quantities related to the rotation of a rigid body about a fixed axis.	K1		
1.2	Describe the motion of a rigid body using mathematics.	K1		
2	Skills:			
2.1	Solve problems related to the rotation of a rigid body about a fixed axis using mathematical methods.	S1		
2.2	Explain the formulas related to Lagrange's equations.	S2		
3	Values:			
3.1	Work effectively and responsibly in teamwork.	V2		
	3 XAB XAB			

## C. Course Content

No	List of Topics	Contact Hours
1	Mechanics of Rigid Bodies, Planar Motion  Center of mass of a rigid body.  Some theorems of static equilibrium of rigid body.  Rotation of a rigid body about a fixed axis (moment of inertia).  Calculation of the moment of inertia.  The physical pendulum.  General theorem concerning angular momentum.  Laminar motion of rigid body.  Body rolling down in inclined plane.	14
2	Motion of Rigid Bodies in Three Dimensions  Angular momentum of a rigid body, Products of inertia.  Use of matrices in rigid body dynamics (the inertia tensor).  Determination of principle axes.  Rotational kinetic energy of a rigid body.  Moment of inertia of a rigid body about an arbitrary axis, the momental ellipsoid.  Euler's equation of motion of a rigid body.  Free rotation of a rigid body under no forces. Geometric description of the motion.  Free rotation of a rigid body with an axis of symmetry. Analytical treatment.	14
3	Lagrangian Mechanics  Generalized coordinates.  Lagrange's equations.  Some Applications of Lagrange's equations.  Generalized moments ignorable coordinate.  Lagrange's equations for impulsive forces.  Hamilton's variational principle.  The Hamiltonian function (Hamiltonian equation).  Lagrange's equations of motion with constraints.	12
	Total	40

## D. Teaching and Assessment

# 1. A lignment of Course Learning Outcomes with Teaching Strategies and Assessment Methods

Course Learning Outcomes	Teaching Strategies	Assessment Methods
Knowledge and Understanding		
Define the physical quantities related to the rotation of a rigid body about a fixed axis.  Describe the motion of a rigid body using mathematics.	1. Demonstrating the basic principles through lectures. 2. Discussing phenomena with illustrating pictures and diagrams. 3. Lecturing method: Board, Power point. 4. Discussions 5. Brain storming Start each chapter by general idea and the	- Solve some examples - Discussions during the lectures Exams: a) Quizzes. b) Midterm exams. c) Final exam.
Sirilla	benefit of it.	
Solve problems related to the rotation of a rigid body about a fixed axis using mathematical methods.	Preparing main outlines for teaching.     Following some	Exams:     a) Quizzes.     b) Midterm exams.
Explain the formulas related to Lagrange's equations.	proofs.  3. Define duties for each chapter	c) Final exam  2. Homework's.
Values	**	
Work effectively and responsibly in teamwork.	<ul> <li>Organize the students in a small groups (teamwork).</li> <li>Give students tasks of duties as a small project.</li> </ul>	<ul> <li>Evaluate the scientific reports.</li> <li>Discussing the reports with each teamwork.</li> <li>Evaluate the efforts of each student in preparing the report.</li> </ul>
	Explain the formulas related to Lagrange's equations.  Knowledge and Understanding  Define the physical quantities related to the rotation of a rigid body about a fixed axis.  Describe the motion of a rigid body using mathematics.  Skills  Solve problems related to the rotation of a rigid body about a fixed axis using mathematical methods.  Explain the formulas related to Lagrange's equations.  Values  Work effectively and responsibly in	Define the physical quantities related to the rotation of a rigid body about a fixed axis.

### 2. Assessment Tasks for Students

#	Assessment task*	Week Due	Percentage of Total Assessment Score
1	Midterm Exam	8 <sup>th</sup>	30%
2	Homework's & Quizzes & Reports	All weeks	20 %
3	Final Exam	End of the semester	50%

<sup>\*</sup>Assessment task (i.e., written test, oral test, oral presentation, group project, essay, etc.)

### E. Student Academic Counseling and Support

Arrangements for availability of faculty and teaching staff for individual student consultations and academic advice:

Each student will be supervised by academic adviser in physics department and timetable for academic advice were given to the student each semester. (4hrs per week)

## F. Learning Resources and Facilities

1.Learning Resources

Required Textbooks	Analytical Mechanics by G. R. Fowles and G. L. Cassiday (2005), 7 <sup>th</sup> edition.
Essential References Materials	
Electronic Materials	
Other Learning Materials	<ul> <li>Classical Mechanics by John R. Taylor (2005).</li> <li>Classical Dynamics of Particles and Systems by S. Thornton, and J. Marion (2004), 5<sup>th</sup> edition.</li> </ul>

2. Facilities Required

Item	Resources	
Accommodation (Classrooms, laboratories, demonstration rooms/labs, etc.)	- Classroom	
Technology Resources (AV, data show, Sm art Board, software, etc.)	- Black Board - Data show	
Other Resources (Specify, e.g. if specific laboratory equipm ent is required, list requirements or attach a list)		

G. Course Quality Evaluation

Evaluation Areas/Issues	Evaluators	Evaluation Methods
Effectiveness of teaching Strategies	Students	Questionnaire
Effectiveness of student assessment	Instructor	Exams
Extent of achievement of course learning outcomes	Instructor	Course report
Quality of learning resources	Instructor	Course report

Evaluation areas (e.g., Effectiveness of teaching and assessment, Extent of achievement of course learning outcomes, Quality of learning resources, etc.)

Evaluators (Students, Faculty, Program Leaders, Peer Reviewer, Others (specify)

Assessment Methods (Direct, Indirect)



H. Specification Approval Data

Council / Committee	
Reference No.	
Date	